Verifying the seL4 Microkernel

Formal Proof in Mathematics and Computer Science

Lukas Stevens 21st June 2018



- 1. What is a μ -kernel?
- 2. Design process of seL4
- 3. Formal methods of the correctness proof
- 4. Layers of the correctness proof
- 5. Conclusion

What is a μ -kernel?

What is a kernel anyway?

Necessary abstractions for applications

- Necessary abstractions for applications
- Interaction via system calls

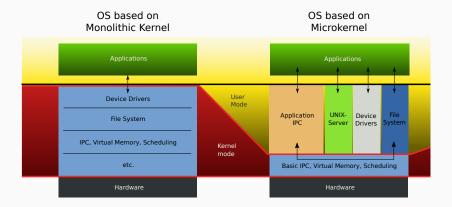
- Necessary abstractions for applications
- Interaction via system calls
- Loaded into protected memory region

- Necessary abstractions for applications
- Interaction via system calls
- Loaded into protected memory region
- \Rightarrow Bugs are potentially fatal

A concept is tolerated inside the μ -kernel only if moving it outside the kernel, i.e. permitting competing implementations, would prevent the implementation of the system's required functionality.

— Jochen Liedtke

Monolithic kernels and μ -kernels



The seL4 $\mu\text{-kernel}$

Member of the L4 μ-kernel family

- Member of the L4 μ -kernel family
- Correctness verified with Isabelle

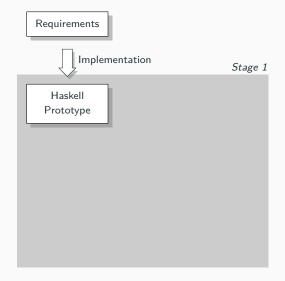
- Member of the L4 μ -kernel family
- Correctness verified with Isabelle
- High performance

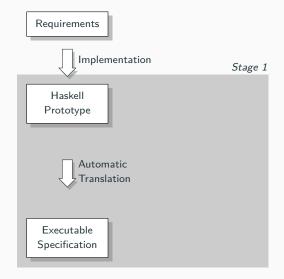
Design process of seL4

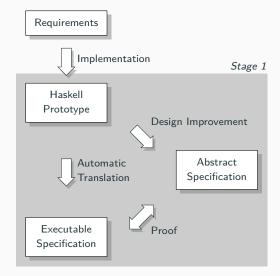
Requirements

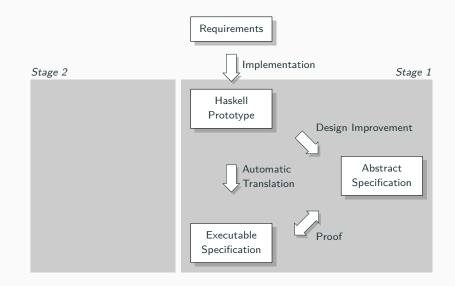
Requirements

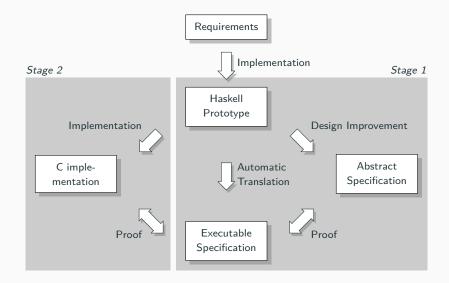
Stage 1











Formal methods of the correctness proof

Hoare logic

$$\overbrace{\{x=1\}}^{P} \quad \overbrace{x:=x+1}^{C} \quad \overbrace{\{x=2\}}^{Q}$$

More Hoare logic

$$\{x = 0 \land x = 1\} \quad y \coloneqq 2 * x \quad \{ \}$$

More Hoare logic

$$\{x \text{ is even}\} \quad y := 2 * x \quad \{ \qquad \}$$

More Hoare logic

$\{x \text{ is even}\}$ $y := 2 * x \{x \text{ and } y \text{ are even}\}$

Partial correctness of Hoare logic

$\{ \ \}$ WHILE true DO c $\{ \ \}$

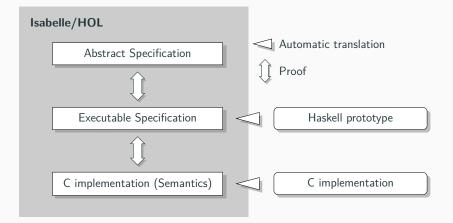
Data refinement

A concrete system C refines an abstract specification A if the behaviour of C is contained in that of A.

- The scheduler selects runnable threads
- System calls return non-zero values on error

Layers of the correctness proof

Proof structure



The abstract specification is the most high-level layer still fully encapturing the behaviour of the kernel.

schedule ≡ do
 threads ← all_active_tcbs;
 thread ← select threads;
 switch_to_thread thread
od OR switch_to_idle_thread

Fill in the details left open by the abstract specification.

```
schedule = do
    action <- getSchedulerAction
    case action of
        ChooseNewThread -> do
            chooseThread
            setSchedulerAction ResumeCurrentThread
chooseThread = do
    r <- findM chooseThread' (reverse [minBound .. maxBound])
    when (r == Nothing) $ switchToIdleThread
chooseThread' prio = do
    q <- getQueue prio
   liftM isJust $ findM chooseThread'' q
chooseThread'' thread = do
    runnable <- isRunnable thread
    if not runnable then do
        tcbSchedDequeue thread
        return False
    else do
        switchToThread thread
       return True
```

```
schedule = do
    action <- getSchedulerAction
    case action of
        ChooseNewThread -> do
            chooseThread
            setSchedulerAction ResumeCurrentThread
chooseThread = do
    r <- findM chooseThread' (reverse [minBound .. maxBound])
    when (r == Nothing) $ switchToIdleThread
chooseThread' prio = do
    q <- getQueue prio
   liftM isJust $ findM chooseThread'' q
chooseThread'' thread = do
    runnable <- isRunnable thread
    if not runnable then do
        tcbSchedDequeue thread
        return False
    else do
        switchToThread thread
       return True
```

Call chooseThread to select next thread.

```
schedule = do
    action <- getSchedulerAction
    case action of
        ChooseNewThread -> do
            chooseThread
            setSchedulerAction ResumeCurrentThread
chooseThread = do
    r <- findM chooseThread' (reverse [minBound .. maxBound])
    when (r == Nothing) $ switchToIdleThread
chooseThread' prio = do
    q <- getQueue prio
   liftM isJust $ findM chooseThread'' q
chooseThread'' thread = do
    runnable <- isRunnable thread
    if not runnable then do
        tcbSchedDequeue thread
        return False
    else do
        switchToThread thread
        return True
```

Call chooseThread to select next thread.

Get runnable thread with highest priority using chooseThread' or schedule idle thread.

```
schedule = do
    action <- getSchedulerAction
    case action of
        ChooseNewThread -> do
            chooseThread
            setSchedulerAction ResumeCurrentThread
chooseThread = do
    r <- findM chooseThread' (reverse [minBound .. maxBound])
    when (r == Nothing) $ switchToIdleThread
chooseThread' prio = do
    q <- getQueue prio
   liftM isJust $ findM chooseThread'' q
chooseThread'' thread = do
    runnable <- isRunnable thread
    if not runnable then do
        tcbSchedDequeue thread
        return False
    else do
        switchToThread thread
        return True
```

Call chooseThread to select next thread.

Get runnable thread with highest priority using chooseThread' or schedule idle thread.

Try to find runnable thread in Queue.

```
schedule = do
    action <- getSchedulerAction
    case action of
        ChooseNewThread -> do
            chooseThread
            setSchedulerAction ResumeCurrentThread
chooseThread = do
    r <- findM chooseThread' (reverse [minBound .. maxBound])
    when (r == Nothing) $ switchToIdleThread
chooseThread' prio = do
    q <- getQueue prio
   liftM isJust $ findM chooseThread'' q
chooseThread'' thread = do
    runnable <- isRunnable thread
    if not runnable then do
        tcbSchedDequeue thread
        return False
    else do
        switchToThread thread
        return True
```

Call chooseThread to select next thread.

Get runnable thread with highest priority using chooseThread' or schedule idle thread.

Try to find runnable thread in Queue.

Check if thread is runnable and act accordingly.

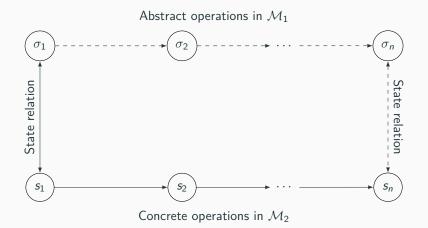
Translate the Haskell implementation to C.

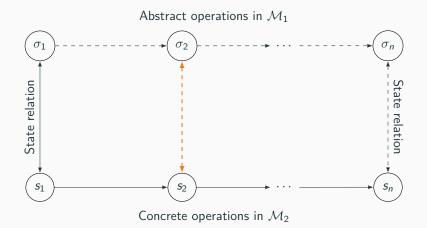
invalidateTLB :: unit machine_m => unit machine_m
invalidateCacheRange ::
 unit machine m => word => word => unit machine m



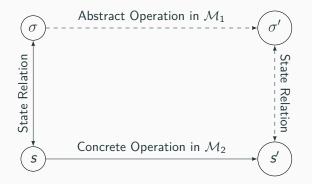








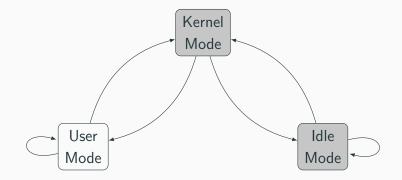
Refinement by forward simulation



Example for forward simulation

On the Board

Types of state transitions



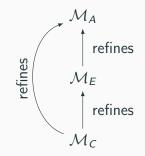
Main result

\mathcal{M}_A

$\mathcal{M}_{\textit{E}}$

$\mathcal{M}_{\mathcal{C}}$

```
\mathcal{M}_A
\uparrow \text{ refines}
\mathcal{M}_E
\uparrow \text{ refines}
\mathcal{M}_C
```



Conclusion

Expenditure of time

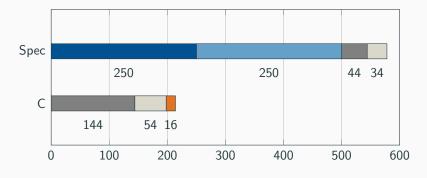
Artefact	Effort (py)	Total (py)
Haskell impl.	2.0	22
C impl.	0.2	
Generic framework	9.0	
Abstract spec. Executable spec.	0.3 0.2	20.5
Refinement $\mathcal{M}_A \leftrightarrow \mathcal{M}_E$ Refinement $\mathcal{M}_E \leftrightarrow \mathcal{M}_C$	8.0 3.0	

How does the effort compare?

• EAL7: 1000 $/LOC \leftrightarrow seL4$: 370/LOC

- EAL7: 1000 $/LOC \leftrightarrow seL4$: 370/LOC
- L4 Pistachio kernel: 6 py \leftrightarrow seL4 kernel: 2.2 py

Changes due to verification



Refinement 1 Refinement 2 Testing



- Correctness proof down to binary level
- Trust in hardware

- Correctness proof down to binary level
- Trust in hardware
- What about Spectre and Meltdown?

The future of seL4

- More architectures
- Multicore support

- More architectures
- Multicore support
- Exclude timing-channel attacks

Questions?